

### Acknowledgements

The authors wish to thank the Union Carbide Corporation and its Linde and Materials Systems Divisions for the fellowship program and technical assistance. Welding materials and cooperation of the International Nickel Company, Inc., Huntington Alloy Products Division are also appreciated.

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## Technical Note: Application of SWAT to the Nondestructive Inspection of Welds

BY C. E. HARTBOWER

SWAT is an acronym for Stress Wave Analysis Technique. Stress waves are produced by the release of elastic energy resulting from the growth of a crack in a stress field. Thus, SWAT constitutes a unique nondestructive inspection method in that the material defect, when propagating, transmits its own signal, with the sensor acting as the receiver. In other words, the material undergoing crack growth both generates and transmits the signal. The SWAT system, consisting of sensors, amplifiers and filters (to eliminate extraneous low-frequency noise) serves as the receiver. System sensitivity can be preset to trigger on a selected signal amplitude, and the operational and reliability status of the system can be checked by periodically inserting a calibration signal. The util-

ity of SWAT as a new, highly sensitive method for monitoring crack growth has been demonstrated in several researches.<sup>1-7</sup>

The objective of the experiment described here was to demonstrate the feasibility of SWAT as a method for obtaining data on delayed weld cracking. In the fabrication of HY-80 submarine hulls, a minimum period of seven days is allowed before nondestructive inspection to be certain that any delayed cracking that might occur will have been completed. Obviously, if a quantitative measurement can be made of the time involved in the delayed cracking process, it may be possible to shorten the minimum time between completing a weld and nondestructive inspection and, thereby, save submarine production time.

### The Test Weldment

HY-80 steel (MIL-S-16216-G) in the form of 2-in.-wide by 10 in. long by 0.70 in. thick bars were welded to

form a test plate 8 in. wide by 10 in. long. Thus, there were three longitudinal welds 10 in. long joining four 2 in. wide bars. The joint design was simply a square butt; incomplete penetration was deliberate to assure cracking. The welding was done by the tungsten-arc process using a 600 amp, automatic welding unit and Linde-83, 1/16 in. diameter filler metal conforming to AWS-ASTM classification E-70S-G.

The welding sequence is shown in Fig. 1; note that two weldments 4 in. wide by 10 in. long were prepared first, and then joined to make the 8 in. wide x 10 in. long test weldment. Passes 1-4 and 9-10 were fusion passes (without filler metal); passes 5-13 involved filler metal automatically fed into the arc at 20 kw. The arc travel speed was 6 ipm at 350 amp and 10 v. The interpass temperature was not controlled; however, the time between passes was recorded, indicating the interpass temperature to be between 300 and 500° F. Contact-pyrometer readings taken after the final pass showed the weldment to be about 225° F at the time the SWAT system was activated.

### The SWAT System

The weldment was placed in a sound-insulated chamber at 4:30  
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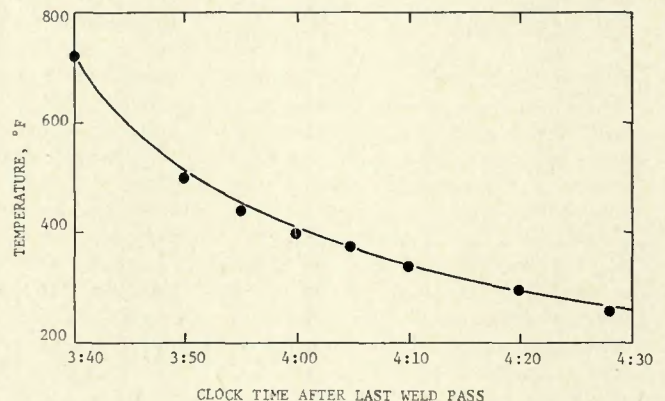
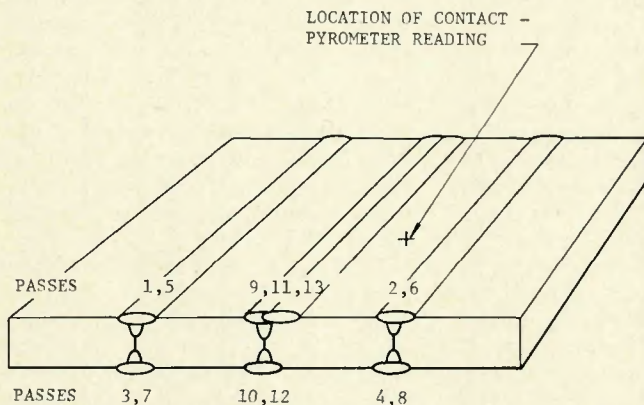


Fig. 1—Weld sequence and temperature



Shuler for doing the welding and much of the associated laboratory work. Thanks are also due to Mr. J. Lynch who helped with the statistical analysis of the data.

The work was performed under U.S. Atomic Energy Commission Contract AT(29-1)-1106. It was sponsored in part by Lawrence Radiation Laboratory.

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P.M.; the SWAT system was activated at 4:41 P.M. Figure 2 is a schematic of the system. With 100X amplifica-

tion followed by a 30 kc high-pass filter and then 1000X amplification, a 38 kc input signal (approximately resonance frequency of mounted accelerometer) is amplified 5000X.

In the counter system, two levels of stress-wave amplitude were recorded. The counter stripchart printout recorded cumulative count and count

rate (number/minute). By a voltage setting, the count-rate printout was adjusted to read signals just above the background noise level. The cumulative count was set to record the larger stress waves, approximately 5X those of the count-rate printout.

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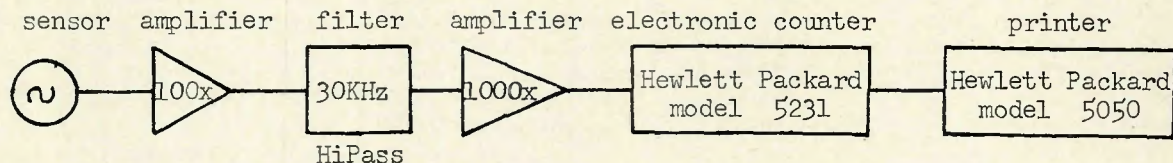


Fig. 2—Schematic representation of the SWAT system

Table 1—Delayed Cracking in Welded HY-80 Steel

Date	Time of Signal	Stress-wave emission		Date	Time of Signal	Stress-wave emission		Date	Time of Signal	Stress-wave emission		
		Cumulative count <sup>a</sup>	Count per minute <sup>b</sup>			Cumulative count <sup>a</sup>	Count per minute <sup>b</sup>			Cumulative count <sup>a</sup>	Count per minute <sup>b</sup>	
3 Apr '69	02:25 PM	(Started welding)		3 Apr '69	34	17		3 Apr '69	37	8		
	03:40	(Welding completed)			35	4567	1146			55	1	
	04:40	(Started counter)			37	5539	3751			07:09	7040	22
	49	0	5		38		27			21	7078	125
	50		10		39	5932	1324			22		89
	51	2	437		40	5955	116			08:11		2
	52		6		42		33			24		1
	56		1		46		18			09:01		1
	58	16	925		48		47			59		44
	05:04		3		52	5955				10:45		76
	07	978	2239		53	6346	1581			11:48		129
	10		28		58		38			4 Apr '69	00:23 AM	90
	14		27		06:00		20			24		8
	15		4		02		2			37	7082	518
	16				04	6998	2166			45		49
	19		20		05	7008	1225			01:03		164
	21		17		07		13			03:03		75
23		40	08	7030	123		04	7107	176			
24		11	09		8		07:41		446			
26		3	20		10		06:53 PM		18			
29	2372	4550	29		2		5 Apr '69	00:15 AM	25			
30		8	31		2		07:19 PM		1			
31	3492	3912	33	7036	35		20	7108 <sup>c</sup>	37			
33	4322	2975	34	7039	16		6 Apr '69	—	—			
							7 Apr '69	07:30 AM	System off			

<sup>a</sup> Counter triggered at 1.0 volt.  
<sup>b</sup> Triggered at 0.25 volt.

<sup>c</sup> Corrected to eliminate system check-out signals.



length and tip position will be found to be vital to a programmed penetration control system.

Some of the considerations may point the way toward improved parameter combinations in pulsed gas tungsten-arc welding, where electrode heating, when it is the prime source of directed heat, does not rise instantaneously but lags the current pulse.

It is clear that generalities about electrode or arc behaviors cannot be made without identification of the electrode shape and background resistances. Transferability of weld parameters from machine to machine in a plant or between plants for a given job has met with problems and scattered results. This has been discouraging since a volt or an ampere should be a fixed quantity anywhere. The position of the instrumentation taps, the resistance drops in the power loop between the instrumentation taps, and the reaction of the resistance to current and time are vital standards for this purpose. The work completed herein has been exploratory. The accuracy of absolute numbers could not be a prime goal of this study. However, the examples, the comparisons, the several cause and effect trends are expected to survive the results of carefully controlled specialized experiments. Some of what is conjecture or speculation can be measured by specific tests.

The influence of electrode shape on the cathode emission surface, the arc and the anode, surface is so significant that those experiments which have failed to specify electrode shape, the length to holder, the cold and hot resistance, or the time of data taking, can only report varieties of trends. In some experiments the failure to recognize resistive heating of the cathode has confounded conclusions. Yet it may be of advantage to the serious scientist to exploit the difference in electrode shapes to isolate the behavior of those sub-systems that ate of so much interest to physicists and welding researches, or to exploit the difference in results given from a cold electrode or a hot electrode, or the resistance rise-rate of various electrode systems.

The resistive components that react negatively to current increase, give a function which drops to a level at 200 amp and is nearly constant through higher currents. The difference in levels for different electrodes and the subtle tendencies with increasing current may contain clues that expose more laws governing cathode emission or the arc.

The resistive components which rise with current give a function  $r_t$  which rises at a constant rate with current. The finer electrodes start and remain higher than the blunter. Each of these functions may be further analyzed

and tested for their representation of real sites of physical events and for their own several components that tell separate stories.

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### Test Results

Table 1 lists the stress waves that were recorded over a period of approximately 87 hr of continuous monitoring. Note that count rate (highest sensitivity setting) recorded the first burst of stress waves 9 minutes after activating the counter system. Note also that the greatest stress-wave activity occurred in the first seven hours (cumulative count of 7078). In the next 24-hour period, the cumulative count increased by only 29, and in the following 24-hour period, the cumulative count increased by only 1. There were no stress waves recorded in the 3rd 24-hr period. Thus, for all practical purposes, the cracking occurred in

the first 24 hr after welding was completed.

### Discussion of Results

The weldment for this test was designed to crack. The square butt joint involved incomplete penetration, and the initial fusion passes were small and cracked before the filler passes were deposited. Thus, the cracking that occurred during welding may have resulted in some degree of stress relief and thereby shortened the period of delayed cracking. Therefore, a quantitative measurement of the duration of delayed cracking will require monitoring restrained joints

that are representative of shipyard practice and free of hot cracking.

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