Thermal Surge in Diffusion Welding—Generation, Inrush Characteristic and Effects

Heating separate members to different temperatures during the DFW process causes dynamic changes in the heat flux and creates the possibility of influencing the microstructure of the joint.

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ABSTRACT. The diffusion welding process (DFW) has, till now, been very thermally stable in comparison with other welding processes. This stability and the favorable economic aspects of DFW are the reasons that methods for process acceleration and diffusion zone formation have been sought. In the present report, a new heating procedure in DFW process is described. In this procedure, termed DFW/TS, the heating of separate members to different temperatures creates, after pressing, a thermal surge in the colder member. Consequently, in the boundary layer of the joint, a thermal spike, a large thermal gradient and heat flux, comes into existence and leads to a sudden increase in the temperature of the colder part. It creates the possibilities of influencing the joint microstructure and the range of plastic deformation.

A simple mathematical model is presented to characterize the thermal surge and evaluate variations of the temperature, thermal spike, thermal gradient and heat flux density at the distance function from surface of contact and in the time function after pressing. The application of these equations to standard welds was required to execute simplifications and approximations. This has made it possible to estimate the data necessary for inrush characteristics and to calculate the variables of DFW/TS. For the example of iron-titanium diffusion welding, the method of measuring temperature, thermal gradient, and heat flux density is presented. The difference in microstructure and microhardness of the diffusion zone is demonstrated by a comparison of the Fe-Ti joints, which have been welded by DFW/TS and conventional DFW.

It was found that the new procedure of heating gives possibilities of controlling thermal energy flow through the contacted surfaces. The temperatures of the members and selection of the member to be heated to the higher temperature have an essential influence on the dynamics of the thermal effects, and thereby, on the joint structure.

Introduction

Modern welding technologies use heat sources which possess a relatively large power output, considerable concentration of thermal flux and the fine control of the heat energy quantity, an essential to joining. For example, in Fig. 1, the electron beam unit (2) can generate concentrated power with a maximum density of \(10^6\) to \(10^8\) \(\text{W/m}^2\). The power of the heat source can be controlled in the range of 1 W to 50 kW, and the diameter of the weld pool is not large, ranging from \(3 \times 10^{-3}\) to \(2 \times 10^{-5}\) m. The equipment for laser beam welding (1), arc welding (3), and electroslag welding (4), in comparison with oxyacetylene welding (5), can be determined from Ref. 1. Apart from the influence on the microstructure of the joint by the thermal regime, a number of welding processes have possibilities of producing metallurgical effects in the weld metal.

As opposed to the above examples, diffusion welding equipment creates very stable thermal conditions without any significant concentration of heat in a boundary layer of the joint. Radiator elements or heating inductors of high frequency are usually employed as thermal sources. Those heating systems can have considerable power with a fine control of the heat energy quantity. By the application of such heating systems, it is impossible in conventional DFW to get a concentration of heat flux in the boundary layer of a diffusion welded joint. It is also impossible to influence the joint's microstructure and to minimize the material's volume heating to high temperature. Therefore, it is generally accepted that diffusion welding is suited for the joining of similar or dissimilar metals which are particularly difficult to join by conventional techniques. However, the factors which have a negative effect on the strength of such joints have already been reported in the literature. Oxide films and intermetallic compounds are of great importance in this matter. Usually very stable and difficult to dissolve, oxide film on the faying surfaces is regarded as one of the most important factors which makes contact between metallic surfaces difficult and which prevents the formation of a metallic fusion between the faying surfaces (Ref. 2). In the second place, a lot of metal combinations form brittle intermetallic compounds in a fusion zone (Ref. 3). The long duration of a DFW process (Fig. 2) and the slow diffusion are conducive to the creation of intermetallic layers (Ref. 4).

Several studies on the prevention of such precipitate formation have been performed, leading to numerous variations of DFW. A few of them are: superplastic forming (SPF/DB) (Ref. 5), hot isostatic pressure (HIP) (Ref. 6), electro-

KEY WORDS

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Separate Members
Dynamic Heat Flow
Thermal Spike
Thermal Diffusion
Oxide Films
Intermetallics
Fe-Ti DFW Joints
static field formed around the pieces to be welded (Ref. 7), flow of the current pulses through the faying surfaces (Ref. 8), torsional vibrations in the planes of the joints (or friction welding in vacuum) causing scuffing (Ref. 9), ultrasonic activation (Ref. 10), constant temperature gradient (Refs. 11, 12) and interlayer metal.

The aim of these DFW variations is to shorten the welding duration of the process. It is realized that the surface oxide films can be crushed and dissolved by accelerating the metallic contact over the largest possible surface and by intensifying the mass transport during the diffusion process. Many well-known DFW variations have defects, the most glaring being expense and limited applications.

The present report describes a new procedure (DFW/TS) of diffusion welding consisting of heating separate members to different temperatures, with the aim of getting thermal surge after pressing (Ref. 13)—Fig. 3. As a result, in the boundary layer of the colder part, a rapid, momentary increase in temperature has taken place, referred to as the thermal spike. The profile of the change in temperature has an influence on thermal gradient value and thermal flux density. Thermal flux flowing through contacted surfaces causes a thermal mass transport known as thermodiffusion (Soret effect). A rapid, momentary increase in temperature in the thin surface layer of the colder part, along with suitable welding variables, can lead to a melting of this layer. This is advantageous in joining metals which are covered by a thin oxide film (Ref. 21). The results indicate that the new heating procedure is simple to apply, shortens the process time, and furthermore, creates extensive possibilities for influencing the structure of the weld zone.

**Experimental Procedure**

**Assumption of the Evaluation**

To characterize the thermal effects occurring in the boundary layer of the colder part after pressing the members together, it is necessary to know the temperature distribution in the thermal field as a function of time and distance from surface contact. From this relation, it is possible to determine the thermal gradient and heat flux density functions.

The values mentioned above, symptomatic of variability in the thermal field, are related to each other and allow thermal effects in the joint to be characterized. These values resulted from the behavior of the heat source, the control range of power, and the physical properties of the jointed metals, all of which have great influence on the structure and quality of the joint. The possibility of measuring or calculating these values creates conditions which establish their influence on the structure of the joint and leads to the optimization of production.

During joining by DFW/TS process, the flow of heat across the contacted surfaces of both parts has dynamic variable values and lasts but a very short time through the thin boundary layer of both metals. For these reasons, the characterization of the thermal effects in joints by measurements of the relevant physical quantity is very difficult. In order to characterize these effects, it was necessary to perform calculations on the basis of the simplified mathematical model. The unlimited bar in the y-axis position, composed of two parts, is described by inequalities \( y_1 \leq 0 \) and \( y_2 \geq 0 \)—Fig. 4A. For each part, suitable thermal conductivities \( \lambda_1, \lambda_2 \); specific heats \( c_{p1}, c_{p2} \); and specific gravities \( g_1, g_2 \) are attributed to both metals. Before contact, in the initial instant \( t = 0 \), the temperature of both parts \( T_1 \) and \( T_2 \) is constant, and \( T_1 > T_2 \). At the moment \( t > 0 \), that is, after contact (Fig. 4B), the temperatures of both connected surfaces are equal, and the contact temperature \( T_c \) is constant in time. However, the heat losses by evaporation and thermal conduction are neglected, and the quantity of the heat flow across the contacted surfaces of the joint is constant in time.

The search distributions of the temperatures \( T_1(y_1, t), T_2(y_2, t) \) and thermal gradients \( \frac{\partial T_1}{\partial y_1}(y_1, t), \frac{\partial T_2}{\partial y_2}(y_2, t) \) as functions of distances \( y_1 \) and \( y_2 \) from the contact place 0 of both parts of the bar at the moment \( t > 0 \) are the aim of the calcula-

![Fig. 1 — Comparison of the constant in time, maximal heat flux density \( q_{max} \) obtained in fusion welding processes performed with selected welding equipment, such as: laser beam (1), electron beam (2), transferred arc (especially submerged arc welding) (3), electroslag (4), and oxyacetylene flame (5). (The heat losses are neglected) The values are presented according to the power output of the welding equipment \( P_{eq} \) and according to the diameter of the weld pool \( d \) (Ref. 1).](image-url)
The course of temperature changes in the conventional diffusion welding (DFW) procedure: $E_1$ and $E_2$ elements to be welded are in contact with each other for the whole time of heating ($t_\text{h}$); welding $t_{\text{DFW}}$ and cooling $t_c$; $T_{\text{DFW}}$, temperature of DFW process; $T_{\text{c}}$, contact temperature of two elements during heating, welding and cooling; $P_i$, initial pressure of elements; $P_{\text{DFW}}$, welding pressure of elements during DFW and cooling; $S_0$, contact surface of both elements.

The required temperatures satisfy the differential equations of heat conduction:

$$\alpha_1 \frac{\partial^2 T_1(y_1,t)}{\partial y_1^2} = \frac{\partial T_1(y_1,t)}{\partial t} \quad (1')$$
$$\alpha_2 \frac{\partial^2 T_2(y_2,t)}{\partial y_2^2} = \frac{\partial T_2(y_2,t)}{\partial t} \quad (1'')$$

and initial conditions:

$$T_1(y_1,0) = T_1' \quad (2')$$
$$T_2(y_2,0) = T_2' \quad (2'')$$

also boundary conditions:

$$T_1(0^-,t) = T_2(0^+,t) \quad (3')$$

$$\lambda_1 \frac{\partial T_1(0^-,t)}{\partial y_1} = \lambda_2 \frac{\partial T_2(0^+,t)}{\partial y_2} \quad (3'')$$

where:

$$\alpha_1 = \frac{\lambda_1}{C_{p1} \beta_1} \quad (4')$$
$$\alpha_2 = \frac{\lambda_2}{C_{p2} \beta_2} \quad (4'')$$

The required temperatures $T_1$, $T_2$ can be represented as a sum of constant functions and of the first kinds of thermal potentials:

$$T_1(y_1,t) = T_1' + \frac{1}{2 \sqrt{\pi}} \int_0^t \frac{\Theta_1(\tau)}{(t-\tau)^2} \exp\left[ -\frac{y_1^2}{4 \alpha_1(t-\tau)} \right] d\tau \quad (5')$$
$$T_2(y_2,t) = T_2' + \frac{1}{2 \sqrt{\pi}} \int_0^t \frac{\Theta_2(\tau)}{(t-\tau)^2} \exp\left[ -\frac{y_2^2}{4 \alpha_2(t-\tau)} \right] d\tau \quad (5'')$$

where: $\Theta_1(\tau)$, $\Theta_2(\tau)$ are any continuous functions for $t > 0$. 

Fig. 2—The course of temperature changes in the conventional diffusion welding (DFW) procedure: $E_1$ and $E_2$, elements to be welded are in contact with each other for the whole time of heating ($t_\text{h}$); welding $t_{\text{DFW}}$ and cooling $t_c$. $T_{\text{DFW}}$, temperature of DFW process; $T_{\text{c}}$, contact temperature of two elements during heating, welding and cooling; $P_i$, initial pressure of elements; $P_{\text{DFW}}$, welding pressure of elements during DFW and cooling; $S_0$, contact surface of both elements.

Fig. 3—The course of temperature changes in DFW/TS during the heating of the separate elements to different temperatures $t_{\text{h}}$; welding $t_{\text{DFW/TS}}$ and cooling $t_c$. $T_{\text{DFW/TS}}$, temperature of DFW/TS in the time $t_{\text{DFW/TS}}$; $T_{\text{c}}$, temperature of surfaces of both elements during welding $t_{\text{DFW/TS}}$ and cooling $t_c$ to the end temperature $T_u$ of the diffusion process; $P_{\text{DFW/TS}}$, welding pressure of elements; $S_0$, contact surface of both elements.
The functions (Equations 5) satisfy the differential equations of heat conduction (Equations 1) and initial conditions (Equations 2).

The fulfillment of the boundary conditions (Equations 3) results in the system of integral equations and functional equations with unknowns \( \Theta_1(r) \) and \( \Theta_2(r) \):

\[
\frac{1}{2} \int_0^1 \frac{\Theta_1(r) - \Theta_2(r)}{\sqrt{t - \tau}} d\tau = T_1 - T_2
\]

\[
\frac{\lambda_1}{\alpha_1} \Theta_1(r) + \frac{\lambda_2}{\alpha_2} \Theta_2(r) = 0
\]

where: \( t > 0 \)

The solution of Equations 6 is a function of:

\[
\Theta_1(r) = - \frac{2\lambda_2 \sqrt{\alpha_1}}{\sqrt{\pi}(\lambda_1 \sqrt{\alpha_2} + \lambda_2 \sqrt{\alpha_1})} (T_1' - T_2') \frac{1}{\sqrt{t}}
\]

\[
\Theta_2(r) = - \frac{2\lambda_1 \sqrt{\alpha_2}}{\sqrt{\pi}(\lambda_1 \sqrt{\alpha_2} + \lambda_2 \sqrt{\alpha_1})} (T_1' - T_2') \frac{1}{\sqrt{t}}
\]

Equations 7 and 5 yield:

\[
T_1(y_1, t) = T_1' - \frac{T_1' - T_2'}{\pi} M_1 \int_0^1 \frac{1}{\sqrt{t} \sqrt{t - \tau}} \exp \left[ - \frac{y_1^2}{4\alpha_1(t - \tau)} \right] d\tau
\]

\[
T_2(y_2, t) = T_2' + \frac{T_1' - T_2'}{\pi} M_2 \int_0^1 \frac{1}{\sqrt{t} \sqrt{t - \tau}} \exp \left[ - \frac{y_2^2}{4\alpha_2(t - \tau)} \right] d\tau
\]

Equations 8 give the temperature \( T_1(y_1, t) \) and \( T_2(y_2, t) \) as a function of the time and distance from the contacted surfaces. The analysis given above is valid if \( y_1 < 0 \), \( y_2 > 0 \) and \( t > 0 \). \( M_1 \) and \( M_2 \) were named the transfer coefficients and, as well as the dimensionless quantity, are described by Equations 9:

\[
M_1 = \frac{\lambda_2 \sqrt{\alpha_1}}{\lambda_1 \sqrt{\alpha_2} + \lambda_2 \sqrt{\alpha_1}}
\]

\[
M_2 = \frac{\lambda_1 \sqrt{\alpha_2}}{\lambda_1 \sqrt{\alpha_2} + \lambda_2 \sqrt{\alpha_1}}
\]

The integral can be solved as below:

\[
\int_0^1 \frac{1}{\sqrt{t} \sqrt{t - \tau}} d\tau = \int \frac{\tau = t \sin^2 s}{d\tau = 2t \sin s \cdot \cos s \, ds} = \int_0^{\pi/2} 2 \, ds = \pi
\]

and Equations 8 and 9 now yield:

\[
T_c = T_1(0, t) = T_2(0, t) = T_1' - \frac{T_1' - T_2'}{\pi} M_1 \int_0^1 \frac{1}{\sqrt{t} \sqrt{t - \tau}} \exp \left[ - \frac{y_1^2}{4\alpha_1(t - \tau)} \right] d\tau
\]

\[
T_2(0, t) = T_2' + \frac{T_1' - T_2'}{\pi} M_2 \int_0^1 \frac{1}{\sqrt{t} \sqrt{t - \tau}} \exp \left[ - \frac{y_2^2}{4\alpha_2(t - \tau)} \right] d\tau
\]

where: \( y_1 = y_2 = 0 \) and \( t > 0 \)

It also follows from Equations 8 and 9 that the thermal gradients as a function of time and distance from the contacted surfaces are:

\[
\frac{\partial T_1}{\partial y_1}(y_1, t) = \frac{M_1}{2\pi\alpha_1} \frac{y_1}{\sqrt{t - \tau}} \int_0^1 \frac{1}{\sqrt{t - \tau}} \exp \left[ - \frac{y_1^2}{4\alpha_1(t - \tau)} \right] d\tau
\]

\[
\frac{\partial T_2}{\partial y_2}(y_2, t) = - \frac{M_2}{2\pi\alpha_2} \frac{y_2}{\sqrt{t - \tau}} \int_0^1 \frac{1}{\sqrt{t - \tau}} \exp \left[ - \frac{y_2^2}{4\alpha_2(t - \tau)} \right] d\tau
\]

Equations 11 can readily be solved, yielding:

\[
\frac{\partial T_1}{\partial y_1}(y_1, t) = - \frac{M_1}{\sqrt{4\alpha_1}} (T_1' - T_2') \exp \left[ - \frac{y_1}{4\alpha_1 t} \right]
\]

\[
\frac{\partial T_2}{\partial y_2}(y_2, t) = - \frac{M_2}{\sqrt{4\alpha_2}} (T_1' - T_2') \exp \left[ - \frac{y_2}{4\alpha_2 t} \right]
\]

where: \( y_1 < 0, y_2 > 0, t > 0 \)
The thermal gradient's uniformity (Equation 12) was derived for four reasons:

1. While the $y_1, y_2$ are variable in the spatial interval $(-\infty, 0^-$), $(0^+, \infty)$ and $t > 0$ is stationary, the limits of the functions are, respectively:

\[
\lim_{y_1 \to -\infty} \frac{\partial T_1}{\partial y_1}(y_1, t) = 0 \\
\lim_{y_2 \to +\infty} \frac{\partial T_2}{\partial y_2}(y_2, t) = 0
\]

The thermal gradients (Equations 12) reach extreme values:

\[
\frac{\partial T_{1x1}}{\partial y_1}(0^-, t) = -M_1 \frac{T_1 - T_2}{\sqrt{\alpha_1 \pi}} \\
\frac{\partial T_{2x2}}{\partial y_2}(0^+, t) = -M_2 \frac{T_1 - T_2}{\sqrt{\alpha_2 \pi}}
\]

where: $y_1 = 0^-, y_2 = 0^+$

2. While $y_1, y_2$ are variable in the spatial interval $(-\infty, 0^-)$, $(0^+, \infty)$ and $t = 0^+$ is stationary, the maximum (in absolute values) thermal gradients (Equations 12) at search distances $y_1$ or $y_2$ from the contact surface are determined by equations:

\[
\frac{\partial T_1}{\partial y_1}(y_1, 0^+) = -M_1 \frac{\sqrt{2}}{y_1 \sqrt{\pi}} (T_1 - T_2) = 0.4839414 \frac{M_1}{y_1} (T_1 - T_2) \\
\frac{\partial T_2}{\partial y_2}(y_2, 0^+) = -M_2 \frac{\sqrt{2}}{y_2 \sqrt{\pi}} (T_1 - T_2) = -0.4839414 \frac{M_2}{y_2} (T_1 - T_2)
\]

where: $y_1 \to 0^-$, $y_2 \to 0^+$

The limits of functions (Equations 16) in the extreme distances interval are, respectively:

\[
\lim_{y_1 \to -\infty} \frac{\partial T_1}{\partial y_1}(y_1, 0^+) = 0 \\
\lim_{y_2 \to +\infty} \frac{\partial T_2}{\partial y_2}(y_2, 0^+) = 0
\]

The functions have any inflection points and extreme values.

3. While $t$ is variable in the time interval $(0, \infty)$ and $y_1 < 0$, $y_2 > 0$ are stationary, the limits of functions in the extreme time interval are:

\[
\lim_{t \to 0^+} \frac{\partial T_1}{\partial y_1}(y_1, t) = 0 \\
\lim_{t \to 0^+} \frac{\partial T_2}{\partial y_2}(y_2, t) = 0
\]

The thermal gradients (Equations 12) reach extreme values:

\[
\frac{\partial T_{1x1}}{\partial y_1}(y_1^+, y_1^2) = \frac{M_1 \sqrt{2}}{y_1 \sqrt{\pi}} (T_1 - T_2) \\
\frac{\partial T_{2x2}}{\partial y_2}(y_2^+, y_2^2) = -\frac{M_2 \sqrt{2}}{y_2 \sqrt{\pi}} (T_1 - T_2)
\]
at the moment:

\[ t_{ex1} = \frac{y_1^2}{2\alpha_1} \]  
\[ t_{ex2} = \frac{y_2^2}{2\alpha_2} \]  

(18')

(18")

The inflection points reach values:

\[ \frac{\partial T_{1(1)} (y_1,t_{1(1)p})}{\partial y_1} = M_1 \frac{T_1 - T_2}{y_1 \sqrt{\pi \left( \frac{1 - \sqrt{6}}{6} \right)}} \exp \left[ -\frac{3 + \sqrt{6}}{2} \right] \]  

(19' p)

\[ \frac{\partial T_{1(2p)} (y_1,t_{1(2)p})}{\partial y_1} = M_1 \frac{T_1 - T_2}{y_1 \sqrt{\pi \left( \frac{1 + \sqrt{6}}{6} \right)}} \exp \left[ -\frac{3 - \sqrt{6}}{2} \right] \]  

(19' 2p)

\[ \frac{\partial T_{2(1)} (y_2,t_{2(1)p})}{\partial y_2} = -M_2 \frac{T_1 - T_2}{y_2 \sqrt{\pi \left( \frac{1 - \sqrt{6}}{6} \right)}} \exp \left[ -\frac{3 + \sqrt{6}}{2} \right] \]  

(19' 3p)

\[ \frac{\partial T_{2(2p)} (y_2,t_{2(2)p})}{\partial y_2} = -M_2 \frac{T_1 - T_2}{y_2 \sqrt{\pi \left( \frac{1 + \sqrt{6}}{6} \right)}} \exp \left[ -\frac{3 - \sqrt{6}}{2} \right] \]  

(19' 2p)

at the moment:

\[ t_{l(1)p} = \left[ \frac{1}{2} - \frac{\sqrt{6}}{6} \right] \frac{y_1^3}{\alpha_1} \]  
\[ t_{l(2p)} = \left[ \frac{1}{2} + \frac{\sqrt{6}}{6} \right] \frac{y_1^3}{\alpha_1} \]  

(20' 1p, 20' 2p)

\[ t_{l(1)p} = \left[ \frac{1}{2} - \frac{\sqrt{6}}{6} \right] \frac{y_2^3}{\alpha_2} \]  
\[ t_{l(2p)} = \left[ \frac{1}{2} + \frac{\sqrt{6}}{6} \right] \frac{y_2^3}{\alpha_2} \]  

(20' 1p, 20' 2p)

4. While \( t \) is variable in the time interval \((0, \infty)\) and \( y_1, y_2 \) are stationary, the maximum (in absolute values) thermal gradients (Equations 12) at the search moment and the optional point of planes, which are parallel to the contact surface and are at a distance \( y_1 = 0^- \) or \( y_2 = 0^+ \), are determined by equations:

\[ \frac{\partial T_1}{\partial y_1} (0^-, t) = -M_1 \frac{T_1 - T_2}{\sqrt{\alpha_1 t}} \]  

(21')

\[ \frac{\partial T_2}{\partial y_2} (0^+, t) = -M_2 \frac{T_1 - T_2}{\sqrt{2 \alpha_2 t}} \]  

(21")

where \( t \to 0 \)

The limits of functions (Equations 21) in the extreme time interval are, respectively:

\[ \lim_{t \to 0^+} \frac{\partial T_1}{\partial y_1} (0^-, t) = -\infty \]  
\[ \lim_{t \to \infty} \frac{\partial T_1}{\partial y_1} (0^-, t) = 0 \]

\[ \lim_{t \to 0^+} \frac{\partial T_2}{\partial y_2} (0^+, t) = -\infty \]  
\[ \lim_{t \to \infty} \frac{\partial T_2}{\partial y_2} (0^+, t) = 0 \]

The functions (Equations 21) have any inflection points and extreme values.
Evaluation of the Temperature, Thermal Gradient and Heat Flux Density Variation for the Unlimited Fe-Ti Binary Bar

In the present investigation, the DFW/TS of technically pure iron to titanium was performed as an example of joining dissimilar metal combinations which form intermetallic compounds. Both metals have allotropic variations at high temperature—Fig. 5. Iron and titanium form a binary system characterized by unlimited solubility of components in a liquid state, by a limited solubility in the solid state and by two intermetallic phases, and they are also stable at low temperature, viz., FeTi and Fe2Ti (Ref. 14). Based on the analysis of the structures of both metals at high temperature and of the diffusion coefficients (Ref. 15), in the present calculation it was accepted that the iron part is heated to a higher temperature. The temperatures of both parts were selected so that the contact temperature $T_c$ was always higher than the transformation point $T_{tr} = T_{tr}^{0}$, viz., $1166 K$—Fig. 5.

The characteristic of the thermal effects during DFW/TS was made in this case when the unlimited binary bar is composed of iron and titanium parts, the difference in temperature of the parts was $300^\circ$, and the iron and titanium were heated separately, but at the same time, to 1423 K and 1123 K, respectively, before joining. The calculations take into account the variations of $\lambda$, $c_p$ and $g$ of both metals with respect to temperature (Ref. 16). Simultaneously, because at high temperature the variations are not great, the approximation was made and the average values from the temperature ranges were used—Table 1. The contact temperature $T_c$ was calculated on the basis of Equations 10. The temperatures for finding the quantity of the temperature variations in the stationary time—Fig. 6. The curves allow possibilities for finding the quantity of the temperature of the arbitrary point in the specified time, measured from the moment of contact of the surfaces. For example, the point $y_2$, which is $1 \cdot 10^{-3}$ m distant from the place of connected surfaces 0, after time $t = 1 \cdot 10^{-4}$ s, has increased the temperature from 1123 to 1268 K—Fig. 6, Curve 5'. At this time, at the distance $y_2 = 1 \cdot 10^{-6}$ m, the point temperatures have risen to 1303 and 1310 K. At the other points, the temperatures changed in the same manner. (Because the distances $y_1$ and $y_2$ on Figs. 6, 7 and 10 are appointed in logarithmic scale, viz., the iron and titanium diagrams have been removed.)

Figure 7 illustrates the thermal gradient distribution in the same conditions as for temperature variation, viz., in the specified time and at a variable distance from 0. Curves 2, 3 and 4 (Equations 12) are attributed to the definite time $t = 2 \cdot 10^{-5}$, $t = 1 \cdot 10^{-4}$, $t = 1 \cdot 10^{-3}$ s, respectively. The characteristic of the variation of one of them can estimate the depth of layers and intensity of thermal effects which have proceeded in it. For example, at the moment $t = 1 \cdot 10^{-4}$ s (Curve 3'), the extreme value of the thermal gradient when $y_2 = 0^\circ$ is equal to $-4232 \cdot 242^\circ/m$ (Equation 13'), at the distance $y_2 = 3.52 \cdot 10^{-4}$ m (Equation 15') it is equal to $-2566 \cdot 985^\circ/m$ (Equation 14'); and next, in absolute values, it equals $-753^\circ/m$ at the distance $y_2 = 1 \cdot 10^{-4}$ m (Equation 12'). At this time, the point temperature $y_2 = 3.52 \cdot 10^{-5}$ m amounts to 1179 K (Fig. 6, Curve 5') and simultaneously rises. At the times $t = 1 \cdot 10^{-3}$ and $t = 1 \cdot 10^{-2}$ s, it reaches 1264 and 1303 K, respectively (Fig. 6, Curves 6', 7'). Curves 2' and 4' (Fig. 7) show the thermal gradient variations which have different values at the other moments in time. Curve 1' (Fig. 7) illustrates the extreme values of the thermal gradients attained at different points when $y_2 \rightarrow 0$ and $t = 0^\circ$. The values were calculated on the basis of Equation 16. One ought to emphasize that the inflection points $l$ (Equations 14, 15) of Curves 2, 3 and 4 are on Curve 1, which has been drawn on the basis of Equation 16. That is why Equation 16 will be used to calculate the variables of the joining process with DFW/TS.

Figures 8 and 9 illustrate the thermal gradient distribution as a time function at definite points on the iron and titanium parts, respectively. For example, at the point $y_2 = 1 \cdot 10^{-3}$ m and at the time $t = 1 \cdot 10^{-4}$ s, the thermal gradient in the colder, titanium part amounts to $-753^\circ/m$.
390°/m and, in absolute values, it increases (Equation 12) (Fig. 9, Curve 2). In the time \( t_{ex} = 8.06 \times 10^{-6} \) s (Equation 18), it attains the extreme value equal to \(-9.043.514°/m\) (Equation 17). The thermal gradient in absolute values is quickly diminished. After \( t = 1 \times 10^{-4}\) and \( t = 1 \times 10^{-3}\) s, the thermal gradients attain the values equal to \(-4.065.136°/m\) and \(-1.332.972°/m\), respectively. This variation of the thermal gradient in time corresponds with the point temperature \( y_2 = 1 \times 10^{-3} \) m, which increases at the time \( t = 1 \times 10^{-6} \) s, and after the times \( t = 2 \times 10^{-5}\), \( t = 1 \times 10^{-4}\) and \( t = 1 \times 10^{-3}\) s, it attains 1192, 1268 and 1294 K, respectively (Fig. 6, Curves 4, 5 and 6). Later, at the time \( t = 1 \times 10^{-2}\), the thermal gradient is equal to \(-423.054°/m\), and the temperature is 1303 K. At the points \( y_2 = 5 \times 10^{-5}\) and \( y_2 = 1 \times 10^{-4} \) m (Fig. 9, Curves 3, 4), the thermal gradient changes in the same manner, but the corresponding, absolute values are lower. Curve 1 (Fig. 9) illustrates the maximum values of the thermal gradient attained at the definite points \( y_2 = 0\) when \( t \to 0\). The shape of this curve is similar to Curve 1 (Fig. 7), but this diagram has the time axis. The character and evaluation of the thermal gradient are similar, and the maximum intensity of the thermal effect is characterized in the thermal boundary layer of both metals. The values were calculated on the basis of Equation 21. Equation 21 will be used to calculate the variables of the joining process with DFW/TS.

Similarly, in the hotter iron part, at the point \( y_1 = 1 \times 10^{-5} \) m (Fig. 6), the thermal gradient increases in absolute values, and at the times \( t = 1 \times 10^{-6} \) s, and \( t = 1 \times 10^{-5}\) and \( t = 1 \times 10^{-4}\) s, it attains \(-567.652°/m\) and \(-5.474.578°/m\), respectively. Next, the thermal gradient diminishes in absolute values, and at the times \( t = 2 \times 10^{-5}\), \( t = 1 \times 10^{-4}\) and \( t = 1 \times 10^{-3}\) s, it attains the values equal to \(-4.592.736°/m\), \(-2.388.953°/m\) and \(-7.81.578°/m\), respectively (Equation 12). The temperature of this point diminishes in time function and attains 1192, 1369, 1352, 1327 and 1313 K, respectively (Fig. 6, Curves 3, 4, 5 and 6). In the iron

---

**Table 1—The Values of Thermal Conductivities (\( \lambda \)), Specific Heats (\( c_p \)), Specific Gravities (\( g \)), and Thermal Conductances (\( \alpha \)) of Iron and Titanium Heated to Different Temperatures.** (The values for transfer coefficients \( M_1 \) and \( M_2 \) are also given)

<table>
<thead>
<tr>
<th>Temperature</th>
<th>( \lambda_1 )</th>
<th>( c_p1 )</th>
<th>( g_1 )</th>
<th>( \alpha_1 )</th>
<th>( M_1 )</th>
<th>( M_2 )</th>
<th>( \lambda_2 )</th>
<th>( c_p2 )</th>
<th>( g_2 )</th>
<th>( \alpha_2 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>298</td>
<td>73</td>
<td>439</td>
<td>7870</td>
<td>2.1129 x 10^{-3}</td>
<td>0.3213467</td>
<td>0.6786533</td>
<td>24</td>
<td>523</td>
<td>4505</td>
<td>1.0186 x 10^{-5}</td>
</tr>
<tr>
<td>1200</td>
<td>29</td>
<td>585</td>
<td>7668</td>
<td>6.4648 x 10^{-6}</td>
<td>0.3747569</td>
<td>0.6252271</td>
<td>17</td>
<td>628</td>
<td>4378</td>
<td>6.1832 x 10^{-6}</td>
</tr>
<tr>
<td>1300°C</td>
<td>29</td>
<td>578</td>
<td>7581</td>
<td>6.1822 x 10^{-6}</td>
<td>0.3770827</td>
<td>0.629069</td>
<td>17</td>
<td>628</td>
<td>4362</td>
<td>6.2058 x 10^{-5}</td>
</tr>
<tr>
<td>1400</td>
<td>30</td>
<td>615</td>
<td>7531</td>
<td>6.4772 x 10^{-6}</td>
<td>—</td>
<td>—</td>
<td>17</td>
<td>628</td>
<td>4362</td>
<td>—</td>
</tr>
</tbody>
</table>

*(a) The values used in the present calculations.*

---

Fig. 5—Illustration of criteria for selecting the contact temperature for the DFW/TS process joining iron and titanium as determined by the crystalline formation. The temperature ranges 1, 2 and 3 have been separated for investigation. Under the symbol for the types of unit cells of crystal lattices, the parameters \( a \) and \( c \) of the lattice and the interatomic distances \( d \) are quoted in angstroms (Å) (Refs. 15, 20)
Fig. 6 — Temperature distribution in the boundary layer of iron and titanium parts which have been brought into contact after heating to different temperatures $T_1 = 1423$ K and $T_2 = 1123$ K, respectively. The curves illustrate the temperature changes at the distances $y_1$ and $y_2$ from contact surface for different values of time after contact, viz., $t > 0$ (Fig. 4B).

Fig. 7 — Thermal gradient distribution in the boundary layer of iron and titanium parts which have been brought into contact after heating to temperatures $T_1 = 1423$ K and $T_2 = 1123$ K, respectively. The curves illustrate the thermal gradient changes at the distances $y_1$ and $y_2$ from the contact surface for different values of time after contact, viz., $t > 0$. $I_p$ — the inflection points of Curves 2, 3 and 4.
The thermal gradient values in the surface layer of the colder part as the distance function \( y_2 \) from the connected surfaces. For example, when the iron and titanium parts were heated to 1423 and 1123 K, respectively, the difference in temperature before joining was 300°. After pressing both parts to each other, the maximum heat flux density obtained in the titanium colder part at the distance \( y_2 = 1 \cdot 10^{-6} \text{ m} \) from connected surfaces is \( q_{y_2 \text{max}} = 1.537 \cdot 10^9 \text{ kW/m}^2 \) (Fig. 11, Line 3).

Apart from this, it is possible to select the difference \( T_1 - T_2 \) and the level of the temperature heating for both parts. It creates the possibility for fine control of the heat energy quantity essential to joining, viz., the thermal spike. For example, at the distance \( y_2 = 1 \cdot 10^{-6} \text{ m} \) from the contact, when \( T_1 - T_2 = 300°, 200° \text{ or } 100° \), the heat flux density amounts to \( 1.537 \cdot 10^9, 1.02 \cdot 10^9 \text{ or } 5.12 \cdot 10^8 \text{ kW/m}^2 \), respectively, for the elementary surface of the colder part. Temperature of the titanium part \( T_2 \) is a constant 1123 K—Table 2 and Fig. 11, Lines 1°, 2°, 3°.

2. While the time is variable, Formula 22 with Equations 21 yields:

\[
q_{y_1 \text{max}} = -\lambda \frac{\partial T}{\partial y} y_1 (T_1 - T_2) =
-0.4839414 \frac{\lambda_1 M_1}{y_1} (T_1 - T_2) \tag{22'}
\]

\[
q_{y_2 \text{max}} = \lambda_2 M_2 \frac{\partial T_{y_2}}{T_1 - T_2} =
0.4839414 \frac{\lambda_2 M_2}{y_2} (T_1 - T_2) \tag{23''}
\]

where: \( \lambda \) (thermal conductivity) and \( M \) (transfer coefficient described in Equation 9) are variable in the temperature.

Equation 23'' defines the momentary, maximum value of the heat flux density in the surface layer of the colder part as the distance function \( y_2 \) from the connected surfaces. For example, when the iron and titanium parts were heated to 1423 and 1123 K, respectively, the difference in temperature before joining was 300°. After pressing both parts to each other, the maximum heat flux density obtained in the titanium colder part at the distance \( y_2 = 1 \cdot 10^{-6} \text{ m} \) from connected surfaces is \( q_{y_2 \text{max}} = 1.537 \cdot 10^9 \text{ kW/m}^2 \) (Fig. 11, Line 3).

Apart from this, it is possible to select the difference \( T_1 - T_2 \) and the level of the temperature heating for both parts. It creates the possibility for fine control of the heat energy quantity essential to joining, viz., the thermal spike. For example, at the distance \( y_2 = 1 \cdot 10^{-6} \text{ m} \) from the contact, when \( T_1 - T_2 = 300°, 200° \text{ or } 100° \), the heat flux density amounts to \( 1.537 \cdot 10^9, 1.02 \cdot 10^9 \text{ or } 5.12 \cdot 10^8 \text{ kW/m}^2 \), respectively, for the elementary surface of the colder part. Temperature of the titanium part \( T_2 \) is a constant 1123 K—Table 2 and Fig. 11, Lines 1°, 2°, 3°.

2. While the time is variable, Formula 22 with Equations 21 yields:
Table 2—Instantaneous Maximum Value of the Thermal Gradient and Heat Flux Density in the Surface Layer of the Titanium Part as a Function of the Distance \( y_2 \) and the Difference in Temperatures \( T_1 - T_2 \)

<table>
<thead>
<tr>
<th>( \lambda_2 ) (in 1300 K)</th>
<th>( y_2 )</th>
<th>( q_{\text{max}} ) [KW/m²]</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>300°</td>
<td>200°</td>
</tr>
<tr>
<td>17</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1 \cdot 10^{-7}</td>
<td>-9.0435 \cdot 10^8</td>
<td>-6.029 \cdot 10^8</td>
</tr>
<tr>
<td>1 \cdot 10^{-6}</td>
<td>-9.0435 \cdot 10^7</td>
<td>-6.029 \cdot 10^7</td>
</tr>
<tr>
<td>1 \cdot 10^{-5}</td>
<td>-9.0435 \cdot 10^6</td>
<td>-6.029 \cdot 10^6</td>
</tr>
<tr>
<td>4.2 \cdot 10^{-5}</td>
<td>-2.1532 \cdot 10^6</td>
<td>-1.4135 \cdot 10^6</td>
</tr>
<tr>
<td>1 \cdot 10^{-4}</td>
<td>-9.0435 \cdot 10^5</td>
<td>-6.029 \cdot 10^5</td>
</tr>
<tr>
<td>1 \cdot 10^{-3}</td>
<td>-9.0435 \cdot 10^4</td>
<td>-6.029 \cdot 10^4</td>
</tr>
</tbody>
</table>

Equation 24”, defining the momentary, maximum values of the thermal effects in the surface layer of the colder part in the contact area as a function of the difference in heating temperature for both parts, lapse of the time after contact and on \( \alpha, \lambda, \) and \( M \) are variable in the temperature.

Equation 24”, defines the momentary, maximum value of the heat flux density in the surface layer of the colder part in the time function. The values depend on the heating temperatures \( T_1 \) and \( T_2 \) of both parts, lapse of the time after contact and on \( \alpha, \lambda_2, M_2 \)—Fig. 12 and Table 3.

Comparison of values has been given by Equations 23” and 24”, enabling the values of the thermal effects in the surface layer of the connection and the variability as a time function to be calculated. For example, when the iron and titanium parts have been heated to 1423 and 1123 K, respectively, and have been pressed to each other, for the colder part at the distances of \( y_2 = 1 \cdot 10^{-6} \) and \( y_2 = 1 \cdot 10^{-4} \) m, the momentary, maximum values of the thermal gradient are \(-9.0435 \cdot 10^8 \) and \(-9.0435 \cdot 10^6 \) °C/m (Equation 21”), and the heat flux densities are \(1.5373 \cdot 10^9\) and \(1.5373 \cdot 10^7\) kW/m², respectively (Equation 24”)—Tables 2, 3 and Figs. 11, 12. These values for the thermal gradient (also the heat flux density) were reached in the times of \( t = 2.1901 \cdot 10^{-7} \) and \( t = 2.1901 \cdot 10^{-3} \) s, respectively—Table 3. The time was calculated on the basis of Equations 24” or 25.

Thus, in DFW/TS, it is possible to generate the instantaneous, very large values of heat flux density flow by contacting the surfaces of members to be jointed. The momentary heat flux density can be controlled by changing the levels, and especially the temperature difference, of the parts. With the aim of demonstrating a comparison of the instantaneous heat flux density generated in DFW/TS, the values are presented against the other fusion welding processes—Figs. 11 and 12.

Evaluation of the DFW/TS Process Variables for the Unlimited Fe-Ti Binary Bar

Similar to the conventional DFW, the basic variables in the procedure for DFW/TS are: temperature, the time of welding, and pressure. The selection of heating temperatures for both parts was made based on the analysis of the properties of the metal parts joined at high temperatures. The following factors were taken into consideration: temperatures of transformation points, crystallographic structure, diffusion coefficients, heat compressive strength, and physical properties \( \alpha, c_p, \) and \( g \) at high temperatures. As a rule, it can be said that: 1) the part made from the metal which has the higher transformation temperature, larger diffusion coefficient and heat compressive strength ought to be heated to the higher temperature; 2) the level and difference of heating temperatures are dependent on the transformation temperature points, crystalline structures, and values of \( \alpha, c_p, \) and \( g \) at high temperatures.

The second variable, the welding time, depends on the properties of the joined metals. Variation of the temperature in the boundary layer as a time function needs a detailed discussion on the separate periods of the heating procedure in DFW/TS. Control of these periods raises...
the possibility of influencing the joint microstructure and the plastic deformation range. Depending on the heating procedure of both parts, two cases are distinguishable. The first is applied when the heating of separate members makes the diffusion reaction, viz., formation of intermetallic compounds, impossible in the preweld interval before the welding temperature is reached. The heating of separate members profits by the introduction of the large thermal gradient in the boundary layer, viz., the intensification of thermal diffusion mass transfer. The continuation of the heating process at a definite, constant temperature $T_c$ after pressure brings the joint to perfection.

In this case, the time of DFW/TS includes three periods—Fig. 13A. The first, $t_1$, interval of the thermal surge time is measured from the moment of pressure to the moment at which the contact temperature $T_c$ at the definite distance $y_c$ from the surface contact is obtained. The interval of time $t_1$ is defined as the time of thermal surge heating up for the specified thickness $y_c$ of the boundary layer of the colder part to the contact temperature $T_c$. The second period, $t_2$, is an interval of time measured from the moment at which the boundary layer had been up to the contact temperature $T_c$ to the moment that the temperature of the parts begins to drop after switching off the heating. The $t_2$ period is defined as the time of diffusion welding at the constant temperature $T_c$. The third period, $t_3$, of cooling down is measured at the moment when the temperature drop of the parts begins. The $t_3$ period defines the cooling time from one temperature to the other. In this example, it is the time from the contact temperature $T_c$ to the assumed temperature $T_0$. The periods $t_1$, $t_2$, and $t_3$ define the dwell time of diffusion welding DFW/TS at the temperatures higher than $T_0$.

The second case is applied when the heating of separate members, similar to the situation in the first case, makes the diffusion reaction impossible. The maxi-

![Figure 11](image-url)  
**Fig. 11**—Instantaneous maximum value of the heat flux density in the surface layer of the titanium part as a function of distance $y_2$ and the temperature difference $T_1 - T_2$ to which the parts have been heated before pressing. Temperature of the titanium part was constant: $T_1 = 1123$ K. The values shown are presented against a background of constant time, $t = 0^o$, and maximum heat flux densities obtained with other fusion welding processes (see Fig. 1).

<table>
<thead>
<tr>
<th>$t_2$ (in 1310 K)</th>
<th>$t$ [s]</th>
<th>$q_{max}$ [W/m²]</th>
<th>$G_{3}$ [degrees/m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>17</td>
<td>$1 \cdot 10^{-7}$</td>
<td>$-1.0435 \cdot 10^6$</td>
<td>$-6.0290 \cdot 10^5$</td>
</tr>
<tr>
<td>2.1901 $ \cdot 10^{-7}$</td>
<td>$-1.3383 \cdot 10^7$</td>
<td>$-6.0290 \cdot 10^5$</td>
<td>$-3.0145 \cdot 10^5$</td>
</tr>
<tr>
<td>2.1901 $ \cdot 10^{-6}$</td>
<td>$-1.3383 \cdot 10^7$</td>
<td>$-6.0290 \cdot 10^5$</td>
<td>$-3.0145 \cdot 10^5$</td>
</tr>
<tr>
<td>3.8633 $ \cdot 10^{-6}$</td>
<td>$-2.1352 \cdot 10^6$</td>
<td>$-6.0290 \cdot 10^5$</td>
<td>$-3.0145 \cdot 10^5$</td>
</tr>
<tr>
<td>1.0 $ \cdot 10^{-5}$</td>
<td>$-1.3383 \cdot 10^7$</td>
<td>$-6.0290 \cdot 10^5$</td>
<td>$-3.0145 \cdot 10^5$</td>
</tr>
<tr>
<td>1.0 $ \cdot 10^{-4}$</td>
<td>$-1.3383 \cdot 10^7$</td>
<td>$-6.0290 \cdot 10^5$</td>
<td>$-3.0145 \cdot 10^5$</td>
</tr>
<tr>
<td>2.1901 $ \cdot 10^{-3}$</td>
<td>$-9.0435 \cdot 10^6$</td>
<td>$-6.0290 \cdot 10^5$</td>
<td>$-3.0145 \cdot 10^5$</td>
</tr>
</tbody>
</table>

**Table 3**—Instantaneous Maximum Value of the Thermal Gradient and Heat Flux Density in the Surface Layer of the Titanium Part as a Function of Time and Difference in Temperatures $T_1 - T_2$
mizing the thermal effects, viz., thermal spike, thermal gradient and heat flux, is beneficial to the microstructure of the boundary layer. The metallurgical aspects require shortening to the minimum high temperature influence on the joined metal. In this case, the time of DFW/TS, termed DFW/TS(S) (with thermal spike), includes two periods—Fig. 13B. The \( t_2 \) period is the interval of thermal surge heating up for the specified thickness \( y_i \) of the boundary layer of the colder part to the contact temperature. The \( t_u \) period is the interval for cooling down to the assumed temperature \( T_u \). The periods \( t_2 \) and \( t_u \) define the dwell time of diffusion welding DFW/TS(S) (with thermal spike \( T_u \)) when the dynamic variable of the contact temperature \( T_u \) is higher than \( T_u \), which qualifies the thermal spike duration \( t_2 \).

One ought to emphasize that in both cases it is possible to select the heating temperatures \( T_1 \) and \( T_2 \) of the members so as to get a thin melted film on the surface of the colder member. It can have a beneficial effect in several cases, e.g., if it is necessary to digest the oxide film.

The third variable of DFW/TS is pressure, and it can be described similarly to conventional DFW.

The time interval of each period can be readily calculated in the following terms. \( t_2 \) for the assumed distance \( y_i \) was defined from Equations 16 and 21, yielding:

\[
t_2 = \frac{e}{2 \alpha_2} (y_i)^2
\]  

The \( t_2 \) determines the time for DFW/TS at constant temperature, i.e., as the contact temperature \( T_u \), and is determined by way of experiment.

The \( t_u \) was also determined by way of experimental data. The exponential equation \( T_u = T_2 \cdot \exp (-t_u \cdot \mu) \) (Ref. 17) can be transformed, yielding:

\[
t_u = -\frac{\ln T_u - \ln T_{2}}{\mu}
\]  

where: \( T_u \) is the required temperature of the boundary layer of the joint after the cooling time \( t_u \); \( T_2 \) is the contact temperature calculated by Equation 10; and \( \mu \) is the cooling constant calculated from the characteristic of the cooling rate curve of the specified members from Equation 27:

\[
\mu = -\frac{\ln T_B - \ln T_A}{t_{AB}}
\]  

Quantities \( T_A, T_B \) and \( t_{AB} \) are measured in the initial part of this curve (Fig. 13B), and serve to calculate \( \mu \) as above.

One ought to emphasize that heating of both parts to temperatures which differ from each other only by 10° also causes large thermal effects in the boundary layer, exactly in the subsurface film. As an example, when iron and titanium have been heated to 1170 and 1160 K, respectively, and pressed together, in the titanium part at the distances \( y_2 = 1 \cdot 10^{-3} \text{m} \) and \( y_2 = 1 \cdot 10^{-6} \text{m} \), the instantaneous maximum values of the thermal gradient are \(-3.0257 \cdot 10^9\) and \(-3.0257 \cdot 10^6 \text{°C/m}\), respectively, and the instantaneous maximum values of the heat flux densities are \(5.144 \cdot 10^5\) and \(5.144 \cdot 10^2 \text{W/m}^2\), respectively. While two parts of titanium have been heated to 1180 and 1170 K, after having been pressed together, for the colder part, at the distances \( y_2 = 1 \cdot 10^{-3} \text{m} \) and \( y_2 = 1 \cdot 10^{-6} \text{m} \), the thermal gradients are \(-2.4197 \cdot 10^9\) and \(-2.4197 \cdot 10^6 \text{°C/m}\), and the heat flux densities are \(4.113 \cdot 10^5\) and \(4.113 \cdot 10^2 \text{W/m}^2\), respectively. The values were calculated on the basis of Equations 16 and 23.

Thus, with the DFW/TS process, one can get the thermal effects desired with relative ease whenever the members are heated separately.

The Equation 16 can also be used to evaluate the boundary value of the thermal gradient \( G_{2R} \), which creates metallurgical changes at the assumed or measured distance \( y_{2R} \). For this aim, the Equation 16 can be written as:

\[
G_{2R} = 0.4839414 \frac{M_2}{Y_{2R}} (T_1 - T_2) \quad (28')
\]

\[
G_{2R} = -0.4839414 \frac{M_2}{Y_{2R}} (T_1 - T_2) \quad (28')
\]

**Results**

**Diffusion Zone Structure of a Fe-Ti Joint**

The influence of DFW/TS process variables on the joint structure were demonstrated on the diffusion welding equip...
Fig. 13—Course of contact temperature variable $T_c$ as a time function in the process. A—When, after pressing, the continuation of the heating process for the interval of time $t_1$ brings the joint to perfection, it is termed the DFW/TS process; B—When the metallurgical aspects require shortening to the minimum high temperature influence on the joined metal, it is termed the DFW/TS(S) process, viz., DFW/TS with thermal spike $T_s$. $R_{th_s}$ is the range of thermal activation described by the value of thermal spike ($T_s$) and time of diffusion welding ($t_{DFW/TS}$). Explanations for the other symbols are in the text.

ment type UZD-612 (Ref. 18). The specimens of iron and titanium, 13 mm (0.51 in.) in diameter - 55 mm (2.2 in.) long, were fixed in the welding positioners $W_1$ and $W_2$ at a distance of 10 mm (0.4 in.) from each other and were heated to different temperatures $T_1$ and $T_2$. The specimens were pressed to each other—Fig. 14A. When the temperatures $T_1$ and $T_2$ were stabilized, the specimens were pressed to each other—Fig. 14B.

Technically, pure iron and titanium were used in the experiment. The choice of metal heated to a higher temperature $T_1$ and the temperature difference $T_1 - T_2$ were made on the basis of physical and mechanical properties, and also on the diffusion coefficients of both metals (Ref. 15).

The joint structure was investigated when the variable limitations mentioned below were changed: the temperature difference $T_1 - T_2$ from 10° to 40° and at the same time the contact temperature $T_c$ was always higher than the transition point of Ti, $\beta = 1166$ K; the time $t_{DFW/TS}$ at the constant temperature $T_c$ from 600 to 0 s; the cooling rate from 2° to 40°/s, viz., the time $t_u$; the pressure per unit area from 1 to 20 MPa.

Fig. 14A—Illustration of the DFW/TS manner of heating and joining of iron and titanium specimens. Iron and titanium samples are separately heated to different temperatures $T_1$ and $T_2$, respectively.
The influence of process variables on the joint strength and microstructure were investigated from tensile tests, metallurgical microscopy and microhardness tests. Distribution of Fe and Ti elements in the diffusion boundary zone were analyzed with EPMA, x-ray diffraction patterns and concentration of elements by Auger analysis. The tests indicate that the best mechanical properties and most sharply defined diffusion zone resulted with the DFW/TS process when the Fe and Ti parts were heated to 1423 and 1123 K, respectively, joined with welding pressure 14 MPa, the time interval $t_v = 0$ s, and the joint rapidly cooled at 30°/s. Joints made by DFW/TS(S) process had tensile strengths of 249.82 MPa, while joints made by conventional DFW had 156.20 MPa.

Figure 15 shows the Fe-Ti joint microstructure and microhardness made by DFW/TS(S) procedure. For comparison, Fig. 16 shows the results of a joint made by conventional DFW. The illustrations demonstrate the essential differences of the joints, especially of the thickness and microhardness of layers in the boundary zone.

The distribution curves of iron and titanium, and the variation in relative concentration of Fe and Ti with depth from the surface, indicate that in the joint...
made by DFW/TS or DFW/TS(S) it is possible to obtain the diffusion zone width \((2 \pm 50) \cdot 10^{-6} \text{ m}\), depending on the process variable. The characteristic of the variation of distribution and the relative concentration of both elements revealed that in the diffusion zone no continuous, intermetallic compound layers were present.

The surface of the fractured joints, which have been broken at the diffusion zone, were examined with x-ray diffraction patterns. The diagrams obtained do not reveal the presence of the intermetallic compounds FeTi and Fe2Ti. The joint made by conventional DFW was examined. In this case, the intermetallic compounds FeTi and Fe2Ti were found in the laminar structure (Ref. 19).

From the diagrams made by the electron probe x-ray microanalyzer or by the Auger analysis, or from the photographs of the microstructure, the maximum range of diffusion in the solid state or the structural change can be read. This presents possibilities for calculating the boundary, which is minimal in absolute value, for the quantity of thermal gradient within this range of structure change. For example, at the investigated point \(R\) (Fig. 15A), at the distance \(y_{2R} = 4.2 \cdot 10^{-5} \text{ m}\), at the time \(t_R = e \cdot (4.2 \cdot 10^{-5}); 2 \cdot 6.2056 \cdot 10^{-5} = 3.8633 \cdot 10^{-4} \text{ s}\) (Equation 25), the maximum absolute value of the thermal gradient is \(-2.53 \cdot 17.6^\circ \text{C/m}\) (Equation 28°), and the maximum heat flux density is \(q_{yR} \max = 3.6604 \cdot 10^2 \text{ kW/m}^2\) (Equation 23°) (Figs. 11 and 12). The above calculation can be used for the description of the thermal diffusion conditions as an effect of the thermal surge and of the thermal diffusion coefficient. It can also be used for the relations of the metallurgical process range with the boundary value of the thermal gradient \(G_{yR}\) at this point.

The value of the welding pressure was selected as a function of the heating temperature \(T_1\) and \(T_2\). It was found that the range of thermal deformation in joints made by DFW/TS(S) is considerably smaller in size in comparison to joints made by conventional DFW.

### Calculation of Welding Conditions for Fe-Ti Joints Made with the DFW/TS and DFW/TS(S) Processes

The ratio of the thermal effect interaction range is very small in comparison to the length of the iron and titanium specimens, and the temperature rise time of the colder member is very short. Therefore, in calculating DFW/TS and DFW/TS(S) variables, the possibility of application equations derived for the unlimited binary bar were assumed. The welding conditions for Fe-Ti joints made by DFW/TS(S) were calculated in accordance with the thermal characteristic illustrated in Fig. 13B. The calculation was simplified by the immobilization of thermal conductivities, specific heats and specific gravity values in the contact temperature \(T_2\). Welding conditions data for the Fe-Ti joint are given in Table 4. The results of this study show that acceptance of the above assumption is reasonable.

### Conclusions

The results obtained from evaluations of thermal effects, thermal spike, thermal gradient and heat flux density, as well as investigations of the diffusion zone structure of Fe-Ti joints made by DFW/TS(S), enable the following conclusions to be made:

1. Introduction to diffusion welding of the procedure consisting of heating the separate members to different temperatures generates, after pressing to each other, a thermal surge in the boundary layer of the joint.

2. Thermal surge characteristic investigations, made on the basis of a mathematical model, showed that in the boundary layer of the unlimited bar, composed of iron and titanium parts, large thermal effects, viz., thermal spike, thermal gradient and heat flux, come into existence.

3. The above have an essential influence on the values and dynamics of the thermal variations: the temperature level and temperature difference of the members, and the physical properties at high temperatures of the metals which have been joined, viz., thermal conductivity, specific heat and specific gravity.

4. The maximum momentary heat flux density generated in the boundary layer by DFW/TS procedure attains a value similar to the analogical, but constant in time, values given by the laser or electron beam equipment.

5. The thermal spike, thermal gradient and heat flux generated by DFW/TS procedure provoke thermal diffusion on the boundary layer.

6. Experience with the introduction of the thermal spike to diffusion welding and mathematical formulation of DFW/TS variables enables this procedure to be used in practice and forms the basis for further investigations on the structure and quality of welds made by DFW/TS.

### Table 4—Welding Condition Data for Fe-Ti Joints Made by the DFW/TS(S) Procedure

<table>
<thead>
<tr>
<th>Variables for DFW/TS(S)</th>
<th>Designation</th>
<th>Value</th>
<th>Unit of Measure</th>
<th>Procedure of Calculation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Temperature of iron member</td>
<td>(T_1)</td>
<td>1423</td>
<td>K</td>
<td>Assumption in accordance with Fig. 5</td>
</tr>
<tr>
<td>Temperature of titanium member</td>
<td>(T_2)</td>
<td>1123</td>
<td>K</td>
<td>Assumption in accordance with Fig. 5</td>
</tr>
<tr>
<td>Temperature difference</td>
<td>(T_1 - T_2)</td>
<td>300°</td>
<td>degrees</td>
<td></td>
</tr>
<tr>
<td>Contact temperature</td>
<td>(T_c)</td>
<td>1310</td>
<td>K</td>
<td>Equation 10</td>
</tr>
<tr>
<td>Transfer coefficient</td>
<td>(M_k)</td>
<td>0.6229069</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Distance (y_{2R}) from the research point</td>
<td>(y_{2R})</td>
<td>4.2 \cdot 10^{-5}</td>
<td>m</td>
<td>measured or assumed</td>
</tr>
<tr>
<td>Time of heat up of the specified thickness (y_{2R}) of the boundary layer</td>
<td>(t_{uR})</td>
<td>3.8633 \cdot 10^{-4}</td>
<td>s</td>
<td></td>
</tr>
<tr>
<td>Instantaneous boundary value of the thermal gradient in the investigated point (R) at distances (y_{2R}) from the connected surfaces</td>
<td>(G_{yR})</td>
<td>2.153217 \cdot 10^6</td>
<td>degrees/m</td>
<td></td>
</tr>
<tr>
<td>Instantaneous value of the heat flux density at the investigated point (R)</td>
<td>(q_{yR}\max)</td>
<td>3.6604 \cdot 10^7</td>
<td>kW/m^2</td>
<td>Equation 23°</td>
</tr>
<tr>
<td>Temperature</td>
<td>(T_A)</td>
<td>1400</td>
<td>K</td>
<td>measured (Fig. 13B)</td>
</tr>
<tr>
<td>Time of cooling down</td>
<td>(\tau_{AB})</td>
<td>10</td>
<td>s</td>
<td>measured (Fig. 13B)</td>
</tr>
<tr>
<td>Cooling constant</td>
<td>(\mu)</td>
<td>0.0228515</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>Interval of cooling down of Fe-Ti joint to the assumed temperature</td>
<td>(T_{c} = 1166\ K)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Thermal spike duration</td>
<td>(\tau_{w})</td>
<td>5.10711</td>
<td>K</td>
<td>Assumption in accordance with Fig. 5</td>
</tr>
<tr>
<td>The end temperature for DFW/TS</td>
<td>(T_{c})</td>
<td>1166</td>
<td>K</td>
<td></td>
</tr>
<tr>
<td>Welding pressure</td>
<td>(P_{DFW/TS})</td>
<td>14</td>
<td>MPa</td>
<td>Determined by experiments</td>
</tr>
</tbody>
</table>
Appendix

Symbols Used

1 and 2 symbols designating the hotter and colder part, respectively, and in later calculations, the iron and titanium members, respectively

0 contact surfaces for both parts (members) and the moment of pressing of the parts to each other

distance from contact surfaces, where \(y_1 \leq 0\) and \(y_2 \geq 0, m\)

\(y_1\) specified thickness of the boundary layers of the colder part (Equation 25), m

\(T\) time measured from the moment pressure is applied to both members, s
time defined for the extreme value in calculations, s

t\(t_{ex}\) time of heating up of the specified thickness \(y\) of the boundary layer of the colder member to contact temperature \(T_c\) by the thermal surge (Equation 25), s

t\(t_d\) time of diffusion welding at constant temperature \(T_c\), s

t\(t_m\) cooling time of the joint from one temperature to the other, specific for members and equipment. In these calculations it describes the cooling time of members from \(T_0\) to \(T_1\), s

t\(t_\mu\) time of thermal spike duration, s

t\(DFW/TS\) time of diffusion welding with the thermal surge; contains the periods \(t_0, t_1\)
t\(DFW/TS(S)\) time of diffusion welding with the thermal surge and thermal spike; contains the periods \(t_0, t_1\)

\(T\) temperature of the joint at the variable distance \(y\)

\(T_{ex}\) extreme value of temperature in the calculations, K

\(T_\mu\) optional temperature which defines the end of the diffusion process, K

\(T_0, T_1\) experimental quantities from the cooling curve (Equation 27), K

DFW diffusion welding as defined in AWS A3.0-80, Standard Welding Terminology

DFW/TS diffusion welding with thermal surge

DFW/TS(S) diffusion welding with thermal surge and thermal spike

\(M\) transfer coefficient as the dimensionless quantity (Equation 9)

\(C_{GR}\) instantaneous boundary value of the thermal gradient at the measured distance \(y_{GR}\) (Equation 28)

\(q_{y, max}\) heat flux density as a function (Equation 23), kW/m²

\(q_{y, \alpha, max}\) heat flux density as a time function (Equation 24), kW/m²

\(\lambda\) thermal conductivity, W/m/°K

\(c_p\) specific heat, J/kg/°K

\(\sigma\) specific gravities, kg/m³

\(\alpha\) thermal conductance which occurs in Equation 4 for heat conduction, m²/s

\(\tau\) slack variable for time interval of \(t_{DFW/TS}\)

\(\theta\) determination later from boundary conditions (Equations 6, 7)

\(\mu\) cooling constant described in Equations 26 and 27

\(\frac{dT}{dy}(y,t)\) thermal gradient value at point \(y\) and time \(t, °/m\)

\(\frac{dT_{ex}}{dy}(y,t)\) extreme thermal gradient value at point \(y\) and time \(t_{ex}, °/m\)

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References


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to Participate in
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at the
69th Annual AWS Convention
New Orleans, Louisiana, April 17-22, 1988

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