

Roper theory is applicable for thin plate.

Experimental

Materials

The steels were 80-ton AOD (argon-oxygen decarburization) heats of 18 Cr, 10 Ni, 304 type stainless steels rolled to approximately 1 mm (0.04) thickness. Details including chemical composition and strip thickness are given in Table 1. The S contents of these steels were varied between 20 and 100 ppm, all other elements were kept reasonably constant.

Surface Tension Measurement

The surface tensions of the steels were measured using the levitated drop method (Ref. 8). In this technique, a sample of known mass (m) is levitated in an electromagnetic coil and the natural oscillation frequency (ω) is monitored continuously. The surface tension can be calculated from the Rayleigh formula given in Equation 2.

$$\gamma = 3 \pi m \omega^2 / 8 \quad (2)$$

A sample (approximately 0.4 g) was levitated in an electromagnetic coil, which was connected to a 15 kW, Radyne RF generator operating at 450 Hz. The frequency of the natural oscillation was determined by projecting the image of the molten, oscillating drop onto a photodetector and analyzing the frequency spectrum by means of a Wavetek waveform analyzer. The temperature of the drop was measured by a two-color pyrometer.

The sample was prevented from oxidation by maintaining a continuous flow of purified gas (Ar, He and H₂) flowing through a silica tube that ran through the interior of the coil. The temperature of the drop was adjusted by altering either the ratio of these gases or the power supplied to the coil.

It has been found in practice that a frequency spectrum containing 3 or 5 peaks is obtained and not the single (Rayleigh) frequency (ω_R) predicted by Equation 2. The splitting is due to the effect of electromagnetic pressure, which results in an apparent increase in surface tension. The results obtained in this study were derived from Equation 2, using the central frequency of the spectrum as the Rayleigh frequency. However, recently an expression has been proposed (Ref. 9) for separating the effect of electromagnetic pressure from the surface tension; the true surface tension being derived by Equation 3 where the subscripts 1 to 5 represent the various peaks and ω_T the transitional frequency at about 5 Hz.

Table 2 — Welding Conditions Used in Trials and Results of Welding Penetration or Full Penetration

No	S-Content mass % (ppm)	Strip Thickness mm	Weld Bead Shape				Welding Speed S _w mm/s	Current I Amp	Linear Energy E Jmm ⁻¹	
			Front Width W _f mm	Back Width W _b mm	Depth d mm	d/W _f				
1-1			3.10	1.05			16.7	100	90	
2			2.15	—	0.72	0.33	25	100	60	
3			1.90	—	0.52	0.27	33.3	100	45	
4	0.002	1.15	4.08	2.67			16.7	150	135	
5	(20)		2.88	0.72			25	150	90	
6			2.44	—	0.80	0.33	33.3	150	68	
7			5.32	4.51			16.7	200	180	
8			3.59	1.73			25	200	120	
9			2.70	—	0.95	0.35	—	33.3	200	90
2-1			3.23	2.20			16.7	100	90	
2			2.06	—	0.97	0.47	25	100	60	
3			1.95	—	0.68	0.35	33.3	100	45	
4	0.003	0.97	4.32	3.82			16.7	150	135	
5	(30)		2.94	2.05			25	150	90	
6			2.70	0.76			33.3	150	68	
7			4.61	4.56			16.7	200	153	
8			3.59	3.38			25	200	120	
9			3.15	1.76			33.3	200	90	
3-1			3.03	2.50			16.7	100	90	
2			2.26	1.20			25	100	60	
3			1.82	—	0.94	0.52	33.3	100	45	
4	0.010	0.94	4.02	3.97			16.7	150	135	
5	(100)		3.17	1.97			25	150	90	
6			2.61	1.26			33.3	150	68	
7			5.73	5.46			16.7	200	180	
8			3.91	3.61			25	200	120	
9			2.96	2.79			33.3	200	90	
4-1			2.50	1.15	—	—	16.7	100	90	
2			1.81	—	0.75	0.41	25	100	60	
3			1.58	—	0.58	0.37	33.3	100	45	
4	0.006	1.15	3.65	2.45	—	—	16.7	150	135	
5	(60)		2.73	0.50	—	—	25	150	90	
6			2.13	—	0.72	0.34	33.3	150	68	
7			7.33	7.04	—	—	16.7	200	180	
8			3.34	1.67	—	—	25	200	120	
9			2.90	1.01	—	—	33.3	200	90	
5-1			2.77	0.41	—	—	16.7	100	90	
2			1.86	—	0.68	0.37	25	100	60	
3			1.75	—	0.51	0.29	33.3	100	45	
4	0.004	1.13	4.01	2.83	—	—	16.7	150	135	
5	(40)		2.74	—	1.04	0.38	25	150	90	
6			2.34	—	0.76	0.32	33.3	150	68	
7			7.57	7.01	—	—	16.7	200	153	
8			4.07	2.54	—	—	25	200	120	
9			3.25	1.41	—	—	33.3	200	90	
6-1			3.35	2.67	—	—	16.7	100	90	
2			1.87	0.63	—	—	25	100	60	
3			1.57	—	0.60	0.38	33.3	100	45	
4	0.007	0.95	4.36	4.22	—	—	16.7	150	135	
5	(70)		2.73	1.84	—	—	25	150	90	
6			2.20	0.89	—	—	33.3	150	68	
7			7.18	6.98	—	—	16.7	200	180	
8			4.28	3.92	—	—	25	200	120	
9			3.21	2.46	—	—	33.3	200	90	

(a) Linear energy E is defined as [current (I) × voltage (u) / welding speed (S_w)]
Other welding parameters: Voltage = 15 V; Arc Length = 0.5 mm; Electrode W 2% ThO₂, diam 2.4 mm, tip angle = 60-deg.
Torch gas: Ar + 2% H₂; Flow Rates, front 10 L min⁻¹, back 16 L min⁻¹, ceramic torch nozzle 10-mm diam.

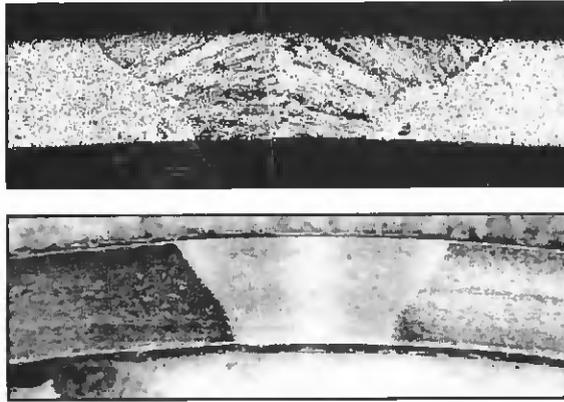


Fig. 11 — Comparison of W_b/W_f ratios obtained for butt joint welds obtained on industrial units with those obtained on small-scale units denoted as curves (taken from Fig. 9); (Ref. 2) number of cathodes used.

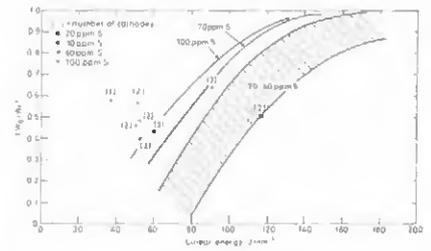


Fig. 12 — The W_b/W_f ratios for small scale welding trials as compared to industrial welding trials.

influenced markedly by welding parameters. The influence of S was found to be only of minor importance in trials where the welding parameters were not tailored to the specific S contents of the casts. Higher S contents do permit higher welding speeds to be achieved, especially on one-electrode plants. However, any gains from increased throughput (*i.e.*, welding speed), must be balanced against the inferior hot and cold workability and corrosion resistance of high-S casts.

Acknowledgment

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CLARIFICATION: *Puckering Phenomenon and its Prevention in GMA Welding of Aluminum Alloys* by H. Miyazaki, et al., pp. 277-s to 284-s, 12/94. Information that did not appear in the original printing of the article has been added to the figures below.

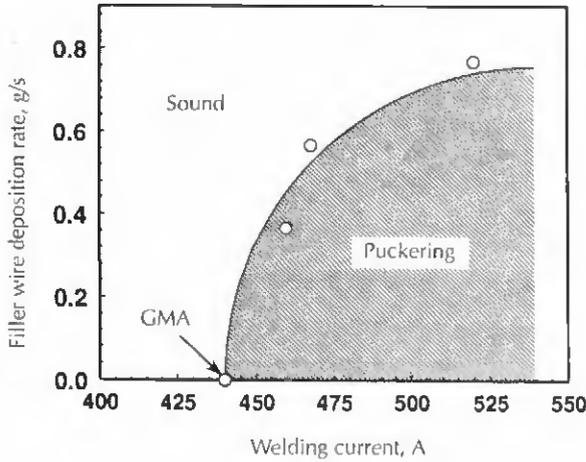


Fig. 4 — Effect of welding current and filler metal wire addition on puckering phenomenon for bead-on-plate experiments. Welding gun angle: 20 deg.

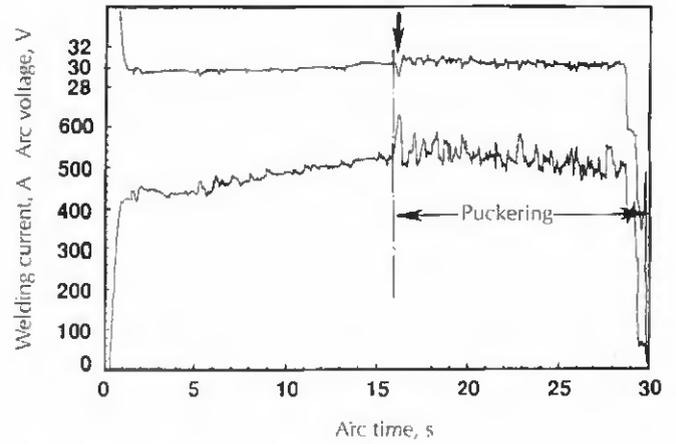


Fig. 5 — Oscillograms of welding current and arc voltage during puckering. Filler metal wire deposition rate: 0.78 g/s.

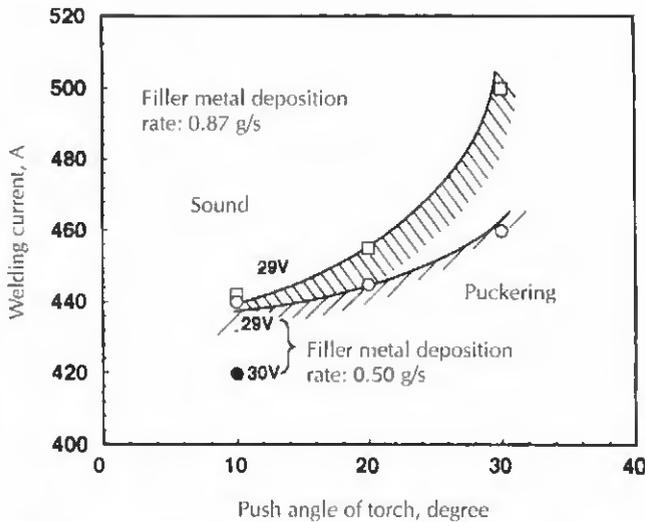


Fig. 6 — Effect of welding gun push angle on the threshold puckering current in the DW GMA welding process. Bead-on-plate weld. Open mark: sound weld; solid mark: puckering bead.

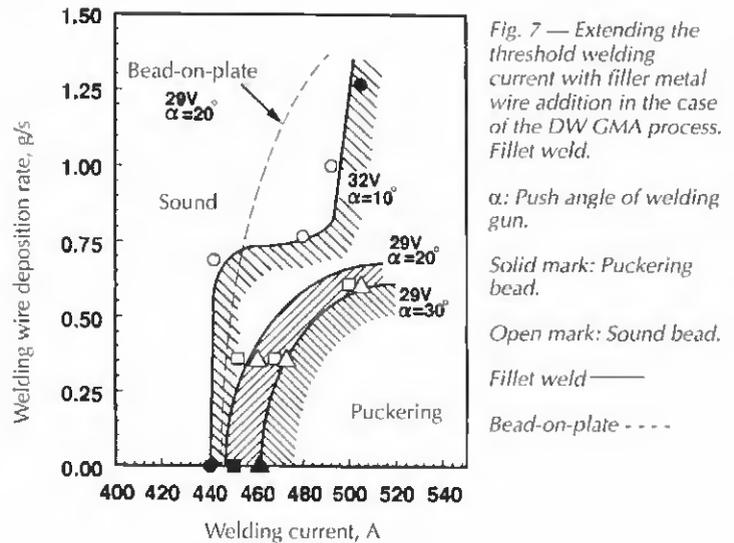


Fig. 7 — Extending the threshold welding current with filler metal wire addition in the case of the DW GMA process. Fillet weld.

α : Push angle of welding gun.

Solid mark: Puckering bead.

Open mark: Sound bead.

Fillet weld —

Bead-on-plate - - -

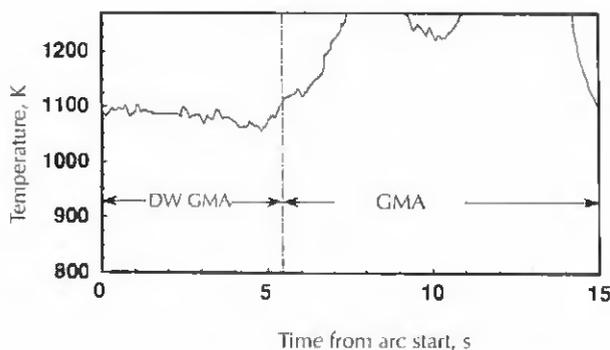


Fig. 9 — Temperature change in the molten pool when changing the welding process from DW GMA to conventional GMA welding.

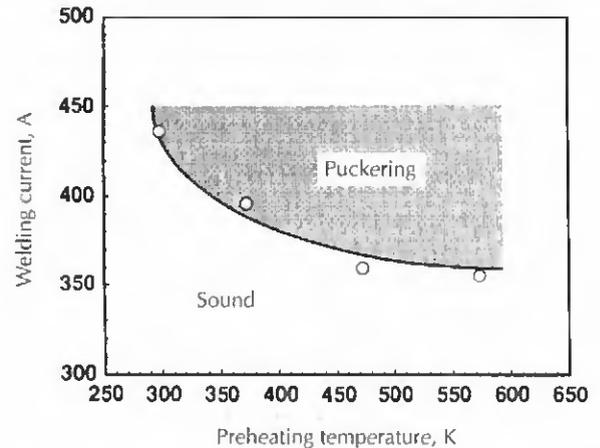


Fig. 10 — Effect of preheating temperature of the base metal on puckering phenomenon.