

depicts the atomic line signal in detecting a small V groove (1 mm). Based on the signal, the groove can be determined. Experiments showed that with argon atomic line intensity signal, 0.2 mm deviation can be reliably detected for a V-type groove with a 1-mm or larger groove leg. For butt joints, the argon atomic line signals can successfully detect square grooves when the minimum root opening is 0.5 mm for GTAW — Fig. 17. However, if an integral arc light signal is used, the minimum root opening increased to 1 mm for GTAW.

Conclusions

This study focused on the theoretical foundation for arc light sensing and its application. The major conclusions drawn from this study are the following:

1) A theoretical model of arc light radiation has been developed for the gas tungsten arc welding process. The model reveals the relationship between welding parameters, arc length and arc light intensity.

2) Spatial distributions of the emission intensities of different elements in the GTAW arc column are significantly different. The spatial emission distributions of argon ions and base metal vapors are not even in the arc column, but that of the argon atom is. By filtering out the argon ionic lines and metal atomic lines, the arc light radiation can reflect the arc length linearly and is in good agreement with the radiation model.

3) With the arc light sensing method, the arc length can be controlled within ± 0.2 mm by making use of the simplified radiation model.

4) The arc light sensing has shown the effectiveness of detecting the deviation of the torch on the weld pass with a V groove and a square groove.

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